1. Cauchy-Schwarz inequality: $|\mathbf{u} \cdot \mathbf{v}| \le ||\mathbf{u}|| ||\mathbf{v}||$ triangle inequality: $||\mathbf{u} + \mathbf{v}|| \le ||\mathbf{u}|| + ||\mathbf{v}||$. Assume Cauchy-Schwarz. Then $\|\mathbf{u} + \mathbf{v}\|^{2} = (\mathbf{u} + \mathbf{v}) \cdot (\mathbf{u} + \mathbf{v}) = \|\mathbf{u}\|^{2} + 2\mathbf{u} \cdot \mathbf{v} + \|\mathbf{v}\|^{2} \le \|\mathbf{u}\|^{2} + 2\|\mathbf{u}\|\|\mathbf{v}\| + \|\mathbf{v}\|^{2} = (\|\mathbf{u}\| + \|\mathbf{v}\|)^{2}.$ 2. (a) $\|\mathbf{u}\| = \sqrt{1+9+4} = \sqrt{14}, \|\mathbf{v}\| = \sqrt{4+1+9} = \sqrt{14}, \mathbf{u} \cdot \mathbf{v} = -2+3-6 = -5,$ $\|\mathbf{u} + \mathbf{v}\| = \sqrt{1 + 16 + 1} = \sqrt{18}.$ (b) Cauchy-Schwarz inequality for these vectors: $|\mathbf{u} \cdot \mathbf{v}| = 5 \le ||\mathbf{u}|| ||\mathbf{v}|| = 14$ triangle inequality for these vectors: $\|\mathbf{u} + \mathbf{v}\| = \sqrt{18} \le \|\mathbf{u}\| + \|\mathbf{v}\| = 2\sqrt{14}$ (c) $(\mathbf{u} + 2\mathbf{w}) \cdot (\mathbf{u} - \mathbf{w}) = \mathbf{u} \cdot \mathbf{u} + (-1 + 2)\mathbf{u} \cdot \mathbf{w} - 2\mathbf{w} \cdot \mathbf{w} = 14 + 13 - 2(25) = -23.$ 3. (a) Calculate $\mathbf{v} \cdot \mathbf{x} = 1 + 0 - 3 = -2$ and $\mathbf{v} \cdot \mathbf{v} = 1 + 4 + 9 = 14$. Then $\mathbf{y} = \frac{\mathbf{v} \cdot \mathbf{x}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = -\frac{1}{7} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$. Hence $\mathbf{z} = \begin{vmatrix} 1\\0\\-1 \end{vmatrix} + \frac{1}{7} \begin{vmatrix} 1\\2\\3 \end{vmatrix} = \frac{1}{7} \begin{vmatrix} 8\\2\\-4 \end{vmatrix}. \text{ Check: } \mathbf{v} \cdot \mathbf{z} = (1/7)(1 \cdot 8 + 2 \cdot 2 - 3 \cdot 4) = 0.$ (b) The vector $\begin{vmatrix} x_1 \\ x_2 \\ x_3 \end{vmatrix}$ is in V^{\perp} when $x_1 + 2x_2 + 3\mathbf{x}_3 = 0$. So $V^{\perp} = \text{Null}(A)$, where $A = \mathbf{v}^T$. Since x_2 and x_3 are the free variables, a basis for the null space is $\mathbf{u}_1 = \begin{bmatrix} -2\\1\\0 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -3\\0\\1 \end{bmatrix}$. (c) Apply Gram-Schmidt to the vectors \mathbf{u}_1 , \mathbf{u}_2 from (b): $\mathbf{v}_{1} = \mathbf{u}_{1} \text{ and } \mathbf{v}_{2} = \mathbf{u}_{2} - \frac{\mathbf{v}_{1} \cdot \mathbf{u}_{2}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}} \mathbf{v}_{1} = \mathbf{u}_{2} - \frac{6}{5} \mathbf{v}_{1} = \frac{1}{5} \begin{vmatrix} -3 \\ -6 \\ 5 \end{vmatrix}. \text{ Check: } \mathbf{v}_{1} \cdot \mathbf{v}_{2} = (1/5)((-2) \cdot (-3) + 1 \cdot (-6) + 0 \cdot 5) = 0,$ $\mathbf{v} \cdot \mathbf{v}_{1} = 1 \cdot (-2) + 2 \cdot 1 + 3 \cdot 0 = 0, \text{ and } \mathbf{v} \cdot \mathbf{v}_{2} = (1/5)(1 \cdot (-3) + 2 \cdot (-6) + 3 \cdot 5) = 0.$ For an orthonormal set use $\mathbf{q}_{1} = \frac{1}{\|\mathbf{v}_{1}\|}\mathbf{v}_{1} = \frac{1}{\sqrt{5}}\begin{bmatrix} -2\\1\\0 \end{bmatrix}$ and $\mathbf{q}_{2} = \frac{1}{\|\mathbf{v}_{2}\|}\mathbf{v}_{2} = \frac{1}{\sqrt{70}}\begin{bmatrix} -3\\-6\\5 \end{bmatrix}.$ (d) The general formula is $c_1 = \mathbf{x} \cdot \mathbf{q}_1 = \frac{-2}{\sqrt{5}}$ and $c_2 = \mathbf{x} \cdot \mathbf{q}_2 = \frac{-8}{\sqrt{70}}$ since $\|\mathbf{q}_1\| = \|\mathbf{q}_2\| = 1$. Check: $c_1\mathbf{q}_1 + c_2\mathbf{q}_2 = \frac{-2}{5} \begin{bmatrix} -2\\1\\0 \end{bmatrix} + \frac{-8}{70} \begin{bmatrix} -3\\-6\\5 \end{bmatrix} = \frac{1}{70} \begin{bmatrix} 80\\20\\-40 \end{bmatrix} = \mathbf{z}.$ 4. Let $R = \operatorname{rref}(A) = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$, basic variables x_1, x_4 and free variables x_2, x_3, x_5 . (a) dim Row $A = \dim \operatorname{Col} A = 2$, dim Null A = 3. (b) For $\operatorname{Col} A = \mathbb{R}^2$, use any orthonormal basis, such as $\begin{vmatrix} 1 \\ 0 \end{vmatrix}$ and $\begin{vmatrix} 0 \\ 1 \end{vmatrix}$. For Row A = Row R, use $\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \end{bmatrix} / \sqrt{3}$ and $\begin{bmatrix} 0 & 0 & 0 & 1 & 1 \end{bmatrix} / \sqrt{2}$. For Null A, the equations are $x_1 + x_2 + x_3 = 0$ and $x_4 + x_5 = 0$, so it has a basis $\mathbf{u}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$. Here $\mathbf{u}_1 \perp \mathbf{u}_3$ and $\mathbf{u}_2 \perp \mathbf{u}_3$. Replace \mathbf{u}_2 by $\mathbf{v}_2 = \mathbf{u}_2 - \frac{\mathbf{u}_2 \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 = \mathbf{u}_2 - \frac{1}{2} \mathbf{u}_1 = \begin{vmatrix} -1/2 \\ -1/2 \\ 1 \\ 0 \\ 0 \end{vmatrix}.$ To get an orthnomal basis $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$, take $\mathbf{w}_{1} = \frac{1}{\|\mathbf{u}_{1}\|} \mathbf{u}_{1} = \frac{1}{\sqrt{2}} \begin{vmatrix} -1 \\ 1 \\ 0 \\ 0 \end{vmatrix}, \quad \mathbf{w}_{2} = \frac{1}{\|\mathbf{v}_{2}\|} \mathbf{v}_{2} = \sqrt{\frac{2}{3}} \begin{vmatrix} -1/2 \\ -1/2 \\ 1 \\ 0 \end{vmatrix}, \quad \mathbf{w}_{3} = \frac{1}{\|\mathbf{u}_{3}\|} \mathbf{u}_{3} = \frac{1}{\sqrt{2}} \begin{vmatrix} 0 \\ 0 \\ 0 \\ -1 \end{vmatrix}.$

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5. The columns of Q must be an orthnormal basis for \mathbb{R}^3 . One solution is $\frac{1}{\sqrt{3}} \begin{bmatrix} 1\\1\\1 \end{bmatrix}$, $\frac{1}{\sqrt{2}} \begin{bmatrix} 1\\0\\-1 \end{bmatrix}$. (There are infinitely many other solutions.)

infinitely many other solutions,)

6. (a) True: There are four distinct eigenvalues, hence four independent eigenvectors.

(b) False: Eigenvalue 0 has algebric multiplicity 2, but only one eigenvector if nullity A = 1.

(c) True: Since nullity A = 4 - 2 = 2, there is a linearly independent set of eigenvectors.

(d) True: Symmetry guarantees that the algebraic multiplicity = geometric multiplicity for eigenvalues, so there is a basis of eigenvectors. The diagonal matrix could have entries 2, 0, 0, 0, or 2, 2, 0, 0, or 2, 2, 2, 0, depending on the multiplicities.

7. (a) Characteristic polynomial det
$$\begin{bmatrix} (7-t) & 0 & 0\\ 0 & (4-t) & 2\\ 0 & 1 & (3-t) \end{bmatrix} = (7-t)(t^2 - 7t + 10) = -(t-2)(t-5)(t-7)$$

Figure values: $\lambda_1 = 2, \lambda_2 = 5, \lambda_3 = 7$
Figure vectors:

Eigenvalues: $\lambda_1 = 2, \lambda_2 = 5, \lambda_3 = 7$. Eigenvectors:

$$\begin{aligned} A - \lambda_1 I_3 &= \begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 1 & 1 \end{bmatrix} \to \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \text{ so eigenvector } \mathbf{v}_1 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}. \text{ (Check: } A\mathbf{v}_1 = \begin{bmatrix} 0 \\ -2 \\ 2 \end{bmatrix} = 2\mathbf{v}_1) \\ A - \lambda_2 I_3 &= \begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 2 \\ 0 & 1 & -2 \end{bmatrix} \to \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}, \text{ so eigenvector } \mathbf{v}_2 = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}. \text{ (Check: } A\mathbf{v}_2 = \begin{bmatrix} 0 \\ 10 \\ 5 \end{bmatrix} = 5\mathbf{v}_2) \\ A - \lambda_3 I_3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -3 & 2 \\ 0 & 1 & -4 \end{bmatrix} \to \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \text{ so eigenvector } \mathbf{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}. \text{ (Check: } A\mathbf{v}_3 = \begin{bmatrix} 7 \\ 0 \\ 0 \end{bmatrix} = 7\mathbf{v}_3) \end{aligned}$$

(b) Take $P = [\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3]$. Then P is invertible since the eigenvectors are independent (the eigenvalues are distinct); alternate argument: det P = 1. Take $D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 7 \end{bmatrix}$ (diagonal matrix of eigenvalues).

8. (a) Take
$$P = [\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3]$$
 and $D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$. Then $P^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & -1 & 1 \end{bmatrix}$ and

 $A = PDP^{-1} = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 1 & 0 \\ -5 & 2 & -1 \end{bmatrix}$ (lower triangular, with eigenvalues on the diagonal). [3]

(b) Let
$$\mathbf{y} = P^{-1}\mathbf{x} = \begin{bmatrix} 1\\1\\7 \end{bmatrix}$$
. Then $\mathbf{x} = P\mathbf{y} = 3\mathbf{v}_1 + 1\mathbf{v}_2 + 7\mathbf{v}_3$. Apply A^n to each eigenvector:
 $A^n\mathbf{x} = 3 \cdot 2^n\mathbf{v}_1 + 1 \cdot 1^n\mathbf{v}_2 + 7 \cdot (-1)^n\mathbf{v}_2 \approx 3 \cdot 2^n\mathbf{v}_1$ when *n* is large.

9. Since $A\mathbf{x} = 2\mathbf{x}$ we have $2\mathbf{x} \cdot \mathbf{y} = (A\mathbf{x}) \cdot \mathbf{y} = (A\mathbf{x})^T \mathbf{y} = \mathbf{x}^T (A\mathbf{y}) = \mathbf{x} \cdot A\mathbf{y}$ since $A = A^T$. But $A\mathbf{y} = 3\mathbf{y}$, so we get $2\mathbf{x} \cdot \mathbf{y} = 3\mathbf{x} \cdot \mathbf{y}$. This forces $\mathbf{x} \cdot \mathbf{y} = 0$.

10. (a) Take
$$\mathbf{v} = \begin{bmatrix} 1\\3\\2 \end{bmatrix}$$
 (column #1 of A). Then $A\mathbf{v} = \mathbf{v}(\mathbf{v}^T\mathbf{v}) = 14\mathbf{v}$, so the eigenvalue is 14.
(b) rref $A = \begin{bmatrix} 1 & 3 & 2\\0 & 0 & 0\\0 & 0 & 0 \end{bmatrix}$, so nullity $(A) = 2$. Hence the zero eigenspace of A has dimension 2. Vectors \mathbf{x} in Null (A) satisfy $x_1 + 3x_2 + 2x_3 = 0$ (free variables x_2 and x_3), so a basis for Null (A) is $\mathbf{u}_1 = \begin{bmatrix} -3\\1\\0 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2\\0\\1 \end{bmatrix}$. Here $\mathbf{v} \cdot \mathbf{u}_1 = \mathbf{v} \cdot \mathbf{u}_2 = 0$ because A is symmetric and \mathbf{v} is an eigenvector with

nonzero eigenvalue.

(c) Apply Gram-Schmidt to the vectors \mathbf{u}_1 , \mathbf{u}_2 as in problem #3:

Let
$$\mathbf{v}_1 = \mathbf{u}_1$$
, $\mathbf{v}_2 = \mathbf{u}_2 - \frac{\mathbf{u}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \mathbf{u}_2 - \frac{6}{10} \mathbf{v}_1 = \begin{bmatrix} -1/5 \\ -3/5 \\ 1 \end{bmatrix}$, $\mathbf{v}_3 = \mathbf{v}$.

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Then $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthogonal basis of eigenvectors for A. Set $\mathbf{q}_i = \frac{1}{\|\mathbf{v}_i\|} \mathbf{v}_i$ to get an orthonormal basis of eigenvectors.

(d) Let $Q = [\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3]$ and $D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 14 \end{bmatrix}$.

11. (a) False in general: Null $A \perp \text{Row } A$ (true if $A = A^T$). (b) True: $Q^{-1} = Q^T$. (c) True: $(P^T Q)^T = Q^T P = Q^{-1} P = Q^{-1} (P^T)^{-1} = (P^T Q)^{-1}$.

- (d) True: Null $A \neq 0$, so $\operatorname{Col} A \neq \mathbb{R}^n$. (e) False in general: $Q^{-1} = Q^T$ (true if $Q = Q^T$). (f) False in general (true if $A = A^T$).

12. (a) $c_j = \mathbf{w}_j \cdot \mathbf{u} = \mathbf{w}_j^T \mathbf{u}$ (product of row vector and column vector). (b) The vector $\mathbf{y} = c_1 \mathbf{w}_1 + \dots + c_k \mathbf{w}_k \in W$ and $\mathbf{u} - \mathbf{y} \perp W$. Hence $\mathbf{y} = \mathbf{w}$ by uniqueness.

(c)
$$C^T \mathbf{u} = \begin{bmatrix} \mathbf{w}_1^T \mathbf{u} \\ \vdots \\ \mathbf{w}_k^T \mathbf{u} \end{bmatrix} = \begin{bmatrix} c_1 \\ \vdots \\ \mathbf{c}_k \end{bmatrix}$$
, so $CC^T \mathbf{u} = c_1 \mathbf{w}_1 + \dots + c_k \mathbf{w}_k = P_W \mathbf{u}$.

(d) The i, j entry in $C^T C$ is $\mathbf{w}_i \cdot \mathbf{w}_j$, which is 1 if i = j and 0 if $i \neq j$. Hence $C^T C = I_k$. Since $W = \operatorname{Col} C$, the general formula $P_W = C(C^T C)^{-1} C^T$ simplifies to $P_W = C C^T$.

13. (a) For a line $y = a_0 + a_1 x$ in the (x, y) plane with y-intercept a_0 and slope a_1 let $E = [9 - (a_0 - 3a_1)]^2 + [7 - (a_0 - a_1)]^2 + [5 - a_0]^2 + [1 - (a_0 + 4a_1)]^2$

This is the sum of the squares of the vertical distance from the given data points to the line. In the method of *least squares* we choose the coefficients a_0 and a_1 to minimize the error E.

(b) The matrix C has first column all 1, and second column the x data values. The vector y has the y data values. The unknown vector \mathbf{u} has the intercept and slope of the line. Hence

$$C = \begin{bmatrix} 1 & -3\\ 1 & -1\\ 1 & 0\\ 1 & 4 \end{bmatrix}, \qquad \mathbf{y} = \begin{bmatrix} 9\\ 7\\ 5\\ 1 \end{bmatrix}, \qquad \mathbf{u} = \begin{bmatrix} a_0\\ a_1 \end{bmatrix}.$$

(c) Since
$$C^T C = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -3 & -1 & 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & -1 \\ 1 & 0 \\ 1 & 4 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & 26 \end{bmatrix}$$
 and $C^T \mathbf{y} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -3 & -1 & 0 & 4 \end{bmatrix} \begin{bmatrix} 7 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 22 \\ -30 \end{bmatrix}$

the equation for **u** is $\begin{bmatrix} 4 & 0 \\ 0 & 26 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} 22 \\ -30 \end{bmatrix}$. Hence $a_0 = 22/4 = 11/2$ and $a_1 = -30/26 = -15/13$. The equation of the best-fitting line is y = (11/2) - (15/13)x.

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