

13.5.3. *Convergence of multistep methods.* Definition: The linear multistep method defined by the formula

$$(13.1) \quad y_{n+1} = \sum_{i=0}^p a_i y_{n-i} + h \sum_{i=-1}^p b_i f_{n-i},$$

is said to be convergent, if for all initial value problems  $y' = f(x, y)$ ,  $y(a) = \eta$ , where  $f$  satisfies hypotheses (A) and (B) of Theorem 10 (i.e.  $f$  defined and continuous and satisfies a Lipschitz condition), we have that

$$(i) \quad \lim_{\substack{h \rightarrow 0, n \rightarrow \infty \\ nh = x - a}} y_n^h = y(x_n)$$

holds for all  $x \in [a, b]$  and all solutions  $\{y_n^h\}$  of the difference equation (13.1) having starting values  $y_k^h$ ,  $k = 0, \dots, p$  satisfying (ii)  $\lim_{h \rightarrow 0} y_k^h = \eta$ ,  $k = 0, \dots, p$ .

Note that this definition requires that (i) be satisfied not only for the sequence  $\{y_n^h\}$  defined with exact starting values  $y(a + kh)$  (for these (ii) is certainly satisfied), but also for all sequences whose starting values tend to the correct starting value  $\eta$  as  $h \rightarrow 0$ . This more stringent condition is imposed, since in practice it is almost never possible to start a computation with exact values.

Remark: To be a convergent method, the approximate solution must converge to the true solution for any problem of a certain class (i.e.,  $f$  Lipschitz continuous in  $y$ ). It is not enough to have convergence for a particular problem.

13.5.4. *Linear difference equations.* One of the methods for analyzing multistep methods for the approximation of ordinary differential equations involves the application of the method to the model problem  $y' = \lambda y$ , where  $\lambda$  is a constant. For this simple problem, the equation defining the numerical method becomes a linear difference equation. We now discuss the solution of such equations.

Definition: A difference equation is a relationship of the form  $f(k, y_k, y_{k-1}, \dots, y_{k-N}) = 0$  between an independent variable  $k$  and an unknown sequence of values  $\{y_k\}$ . A solution of a difference equation is a sequence of numbers  $\{y_k\}$  that satisfies  $f(k, y_k, y_{k-1}, \dots, y_{k-N}) = 0$  for all  $k$  in some set  $I$  of consecutive integers.

Example:  $f(k, y_k, y_{k-1}) = y_k - y_{k-1} - 1 = 0$ . The solution is the sequence  $\{y_k\}$ , where  $y_k = k + C$ , with  $C$  constant and  $I$  is the set of all integers.

Example:  $y_k = qy_{k-1}$ . The solution is the sequence  $\{y_k\}$ , where  $y_k = Cq^k$ , where  $C$  is a constant. In both cases, we obtain a family of solutions depending on the parameter  $C$ . If we are given an initial condition such as  $y_0 = A$  to determine  $C$ , then we have an initial value problem for the difference equation.

Definition: The order of a difference equation is the difference between the largest and smallest subscript (of  $y$ ) appearing in the equation.

Definition: A linear difference equation is a difference equation of the form:

$$a_0(k)y_k + a_1(k)y_{k-1} + \cdots + a_N(k)y_{k-N} = b(k),$$

where  $a_i(k)$  and  $b(k)$  are functions only of  $k$  and do not depend on  $y$ .

Definition: A linear difference equation is called homogeneous if  $b(k) \equiv 0$  for all  $k$ .

We now consider the solution of an  $N$ th order linear homogeneous difference equation with constant coefficients. Since both  $a_0$  and  $a_N \neq 0$ , we take  $a_0 = 1$  (i.e., divide the equation by  $a_0$  and relabel). Thus, the equation has the form

$$y_k + a_1y_{k-1} + \cdots + a_Ny_{k-N} = 0.$$

To solve this equation, we look for solutions of the form  $y_k = z^k$ , where  $z$  is a constant to be determined. Then  $z$  satisfies

$$\begin{aligned} z^k + a_1z^{k-1} + \cdots + a_Nz^{k-N} &= 0, \quad \text{i.e.,} \\ z^{k-N}[z^N + a_1z^{N-1} + \cdots + a_N] &= 0. \end{aligned}$$

This expression will be zero not only when  $z = 0$  (the trivial solution), but also when  $z$  is a root of

$$\rho(z) = z^N + a_1z^{N-1} + \cdots + a_N = 0.$$

$\rho(z)$  is called the characteristic polynomial of the difference equation.

Suppose we solve  $\rho(z) = 0$  and find  $m$  distinct roots  $z_1, \dots, z_m$ , with  $p_\mu$  the multiplicity of  $z_\mu$ . Then  $z_\mu^k, kz_\mu^k, \dots, k^{p_\mu-1}z_\mu^k$  are also solutions of the difference equation. This gives us  $N$  solutions of the difference equation, which turn out to be linearly independent. The general solution of the difference equation is a linear combination of these solutions, i.e.,

$$y_k = \sum_{\mu=1}^m \sum_{j=1}^{p_\mu} C_{\mu j} k^{j-1} z_\mu^k.$$

Since we will assume that the coefficients of our difference equation are real, if  $z$  is a complex root of  $\rho(z)$ , the complex conjugate  $\bar{z}$  is also a root of  $\rho(z)$ , with the same multiplicity, i.e., if  $z = re^{i\theta}$  is a root, so is  $\bar{z} = re^{-i\theta}$ . Hence  $z^k$  and  $\bar{z}^k$  are solutions of the difference equation. The part of the general solution of the difference equation corresponding to these solutions is  $Az^k + B\bar{z}^k$ , where  $A$  and  $B$  are complex. These may be written in terms of real solutions using the following formulas:

$$Az^k = Ar^k e^{i\theta k} = Ar^k [\cos(\theta k) + i \sin(\theta k)], \quad B\bar{z}^k = Br^k e^{-i\theta k} = Br^k [\cos(\theta k) - i \sin(\theta k)],$$

where if  $z = x + iy$  then  $r = \sqrt{x^2 + y^2}$  and  $\theta = \tan^{-1}(y/x)$ . Hence,

$$Az^k + B\bar{z}^k = r^k [(A + B) \cos(\theta k) + i(A - B) \sin(\theta k)]. = r^k [a \cos(\theta k) + b \sin(\theta k)],$$

where  $a = A + iB$  and  $b = i(A - B)$ . Thus, in the formula for the general solution, we can replace the linearly independent complex solutions  $z^k$  and  $\bar{z}^k$  by the linearly independent real solutions  $r^k \cos(\theta k)$  and  $r^k \sin(\theta k)$ .

We obtain the general solution of a linear nonhomogeneous difference equation by adding a particular solution to the general solution of the homogeneous difference equation. A

particular solution can sometimes be found by the method of undetermined coefficients, i.e., by trying a solution of the form constant times the right hand side of the equation.

Example: Suppose an amount  $A$  is borrowed at an interest rate of  $i$  per payment period and must be paid back in  $n$  payments of equal amounts  $S$ . Determine  $S$  in terms of  $A$ ,  $i$ , and  $n$ .

Let  $P_k$  be the principal outstanding after the  $k$ th payments. Then  $P_0 = A$  and  $P_n = 0$ . Now

$$P_{k+1} = P_k + iP_k - S = (1+i)P_k - S.$$

The general solution of the homogenous equation is  $a(1+i)^k$  for any constant  $a$ . Since the right hand side of the equation is constant, we look for a particular solution which is a constant, say  $b$ . Then  $b = (1+i)b - S$ , so  $b = S/i$ . Hence the general solution of the full difference equation is given by  $P_k = a(1+i)^k + S/i$ . Applying the initial condition  $P_0 = A$ , we find that  $a = A - S/i$ . Hence,  $P_k = [A - S/i](1+i)^k + S/i$ . Finally, we determine  $S$  from the condition that  $P_n = 0$ , i.e.,  $[A - S/i](1+i)^n + S/i = 0$ . Hence,

$$S = \frac{Ai(1+i)^n}{(1+i)^n - 1} = A \frac{i}{1 - (1+i)^{-n}}.$$

**Theorem 12.** *A necessary condition for the convergence of linear multistep method is that the method be consistent, i.e.,*

$$1 = \sum_{i=0}^p a_i, \quad 1 = -\sum_{i=0}^p ia_i + \sum_{i=-1}^p b_i.$$

*Proof.* If the method is convergent, then it is convergent for the IVP  $y' = 0$ ,  $y(0) = 1$ , whose exact solution is  $y(x) = 1$ . For this problem, the general linear multistep method becomes  $y_{n+1} = \sum_{i=0}^p a_i y_{n-i}$ . Let the starting values  $y_0, \dots, y_p$  be exact, i.e., equal to 1. Since the method is convergent, we must have that  $y_n^h \rightarrow 1$  as  $h \rightarrow 0$ ,  $n \rightarrow \infty$ , and  $nh = x$ . Hence, letting  $n \rightarrow \infty$  in the expression  $y_{n+1} = \sum_{i=0}^p a_i y_{n-i}$ , we get  $1 = \sum_{i=0}^p a_i$ .

To establish the second equality, we consider the IVP  $y' = 1$ ,  $y(0) = 0$ , whose exact solution is  $y(x) = x$ . The difference equation is now  $y_{n+1} = \sum_{i=0}^p a_i y_{n-i} + h \sum_{i=-1}^p b_i$ . Consider the sequence  $y_n = nhA$ ,  $n = 0, 1, \dots$ , where

$$A = \frac{\sum_{i=-1}^p b_i}{1 + \sum_{i=0}^p ia_i}.$$

We will first show that the sequence  $\{y_n\}$  is a solution of the difference equation. To see this, we compute

$$\begin{aligned} \sum_{i=0}^p a_i y_{n-i} + h \sum_{i=-1}^p b_i &= \sum_{i=0}^p a_i (n-i)hA + h \sum_{i=-1}^p b_i = \sum_{i=0}^p a_i (n-i)hA + hA(1 + \sum_{i=0}^p ia_i) \\ &= hA + hAn \sum_{i=0}^p a_i = (n+1)hA = y_{n+1}, \end{aligned}$$

where we have used the first identity. We next observe that this sequence also satisfies the condition that  $\lim_{h \rightarrow 0} y_n = 0$ ,  $n = 1, 2, \dots, p$ . Since the method is convergent,  $y_n^h \rightarrow x$  as  $h \rightarrow 0$ ,  $n \rightarrow \infty$ , and  $nh = x$ , i.e.,  $nhA = x$  for  $nh = x$ . Hence  $A = 1$ , so the second equality is established.  $\square$