

```

[ > restart:
[ > with(plots):
[ > # let's write what f is, and the two right-hand sides of the ODE
[ > f(x,y):=(x*y^g)/(x*y^g+y^g+1);


$$f(x,y) := \frac{x y^g}{x y^g + y^g + 1}$$

[ > eq1:=nu-f(x,y);


$$eq1 := v - \frac{x y^g}{x y^g + y^g + 1}$$

[ > eq2:=alpha*f(x,y)-eta*y;


$$eq2 := \frac{\alpha x y^g}{x y^g + y^g + 1} - \eta y$$

[ > # now let us find the two nullclines
[ > nul1:=simplify(solve(eq1,y));


$$nul1 := \left( -\frac{v}{v x + v - x} \right)^{\left( \frac{1}{g} \right)}$$

[ > nul2:=simplify(solve(eq2,y)); nul2:=simplify(solve(eq2,y));


$$nul2 := \text{RootOf}(\alpha x \_Z^g - \eta \_Z^{(1+g)} x - \eta \_Z^{(1+g)} - \eta \_Z)$$


$$nul2 := \text{RootOf}(\alpha x \_Z^g - \eta \_Z^{(1+g)} x - \eta \_Z^{(1+g)} - \eta \_Z)$$

[ > # let's pick the constants that the book uses, and substitute into
[ nullcline equations
[ > consts:={nu=0.0285,eta=0.1,alpha=1,g=2};


$$consts := \{v = .0285, \eta = .1, \alpha = 1, g = 2\}$$

[ > nul1:=subs(consts,nul1);

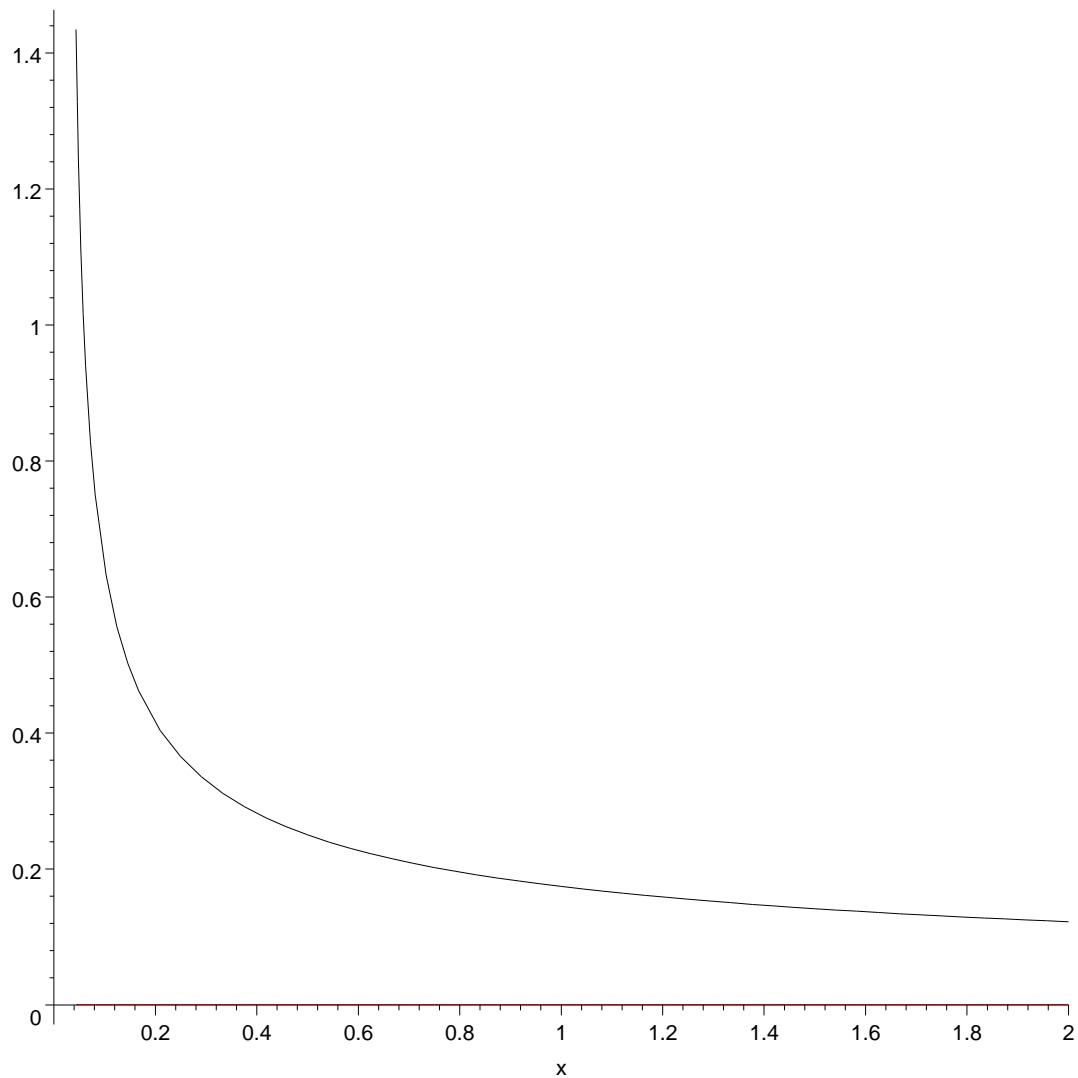

$$nul1 := \sqrt{-0.0285 \frac{1}{-0.9715 x + 0.0285}}$$

[ > nul2:=subs(consts,nul2);


$$nul2 := \text{RootOf}(x \_Z^2 - .1 \_Z^3 x - .1 \_Z^3 - .1 \_Z)$$

[ > # this looks messy, but maybe Maple will be able to handle it (?)
[ > p1:=plot(nul1,x=0..2,thickness=3,color=black):
[ > p2:=plot(nul2,x=0..2,thickness=3,color=red):
[ > display(p1,p2);

```



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[ > # oops, Maple really messed up with that second graph
  > # so maybe it is easier to draw x against y and transpose the
  graphs? Let us see:
```

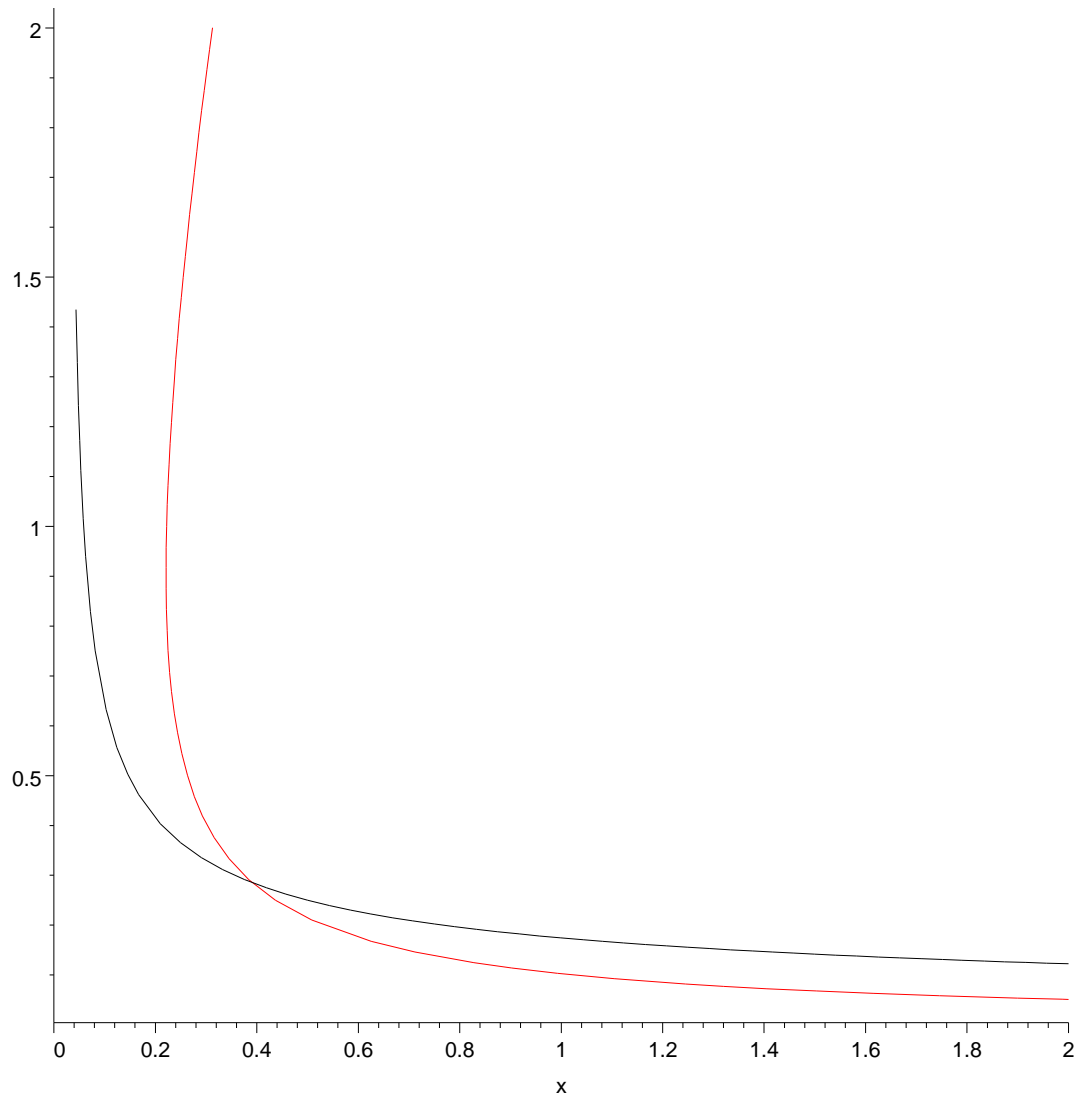
```
[ > nul2transpose:=simplify(solve(eq2,x));
```

$$\text{nul2transpose} := -\frac{\eta y (1 + y^{(-g)})}{-\alpha + \eta y}$$

```
[ > nul2transpose:=subs(consts,nul2transpose);
```

$$\text{nul2transpose} := -.1 \frac{y \left(1 + \frac{1}{y^2} \right)}{-1 + .1 y}$$

```
[ > p2:=plot([nul2transpose,y,y=0..2]):
> display(p1,p2);
```



```
[ > # OK, that's better!
> # but where is that steady state, exactly? Looks like (0.4,0.3)
or so...
> temp1:=simplify(solve({eq1,eq2},{x,y}));
```

$$temp1 := \left\{ x = -\frac{v \left(1 + \left(\frac{\alpha v}{\eta} \right)^{(-g)} \right)}{v-1}, y = \frac{\alpha v}{\eta} \right\}$$

```
[ > X:=subs(temp1,x);
```

$$X := -\frac{v \left(1 + \left(\frac{\alpha v}{\eta} \right)^{(-g)} \right)}{v - 1}$$

```
> Y:=subs(templ,y);
```

$$Y := \frac{\alpha v}{\eta}$$

```
> (subs(consts,X),subs(consts,Y));
```

```
.3905066321, .2850000000
```

```
> # we were close :-)
```

```
> # btw, the book writes everything in terms of 'p':
```

```
> subs(alpha*nu/eta=p,Y);
```

$$p$$

```
> subs(alpha*nu/eta=p,X);
```

$$-\frac{v(1+p^{(-g)})}{v-1}$$

```
> # what about the directions of flow in each of the regions?
```

```
> # when x~0, we have that dx/dt is what sign?
```

```
> eq1;
```

$$v - \frac{xy^g}{xy^g + y^g + 1}$$

```
> subs(x=0,eq1);
```

$$v$$

```
> # so it is positive there; and as x goes to infty, we get nu-1<0  
(nu<1 assumed)
```

```
> # so we have these signs for dx/dt (direction can only change on  
nullclines)
```

```
> with(plottools):
```

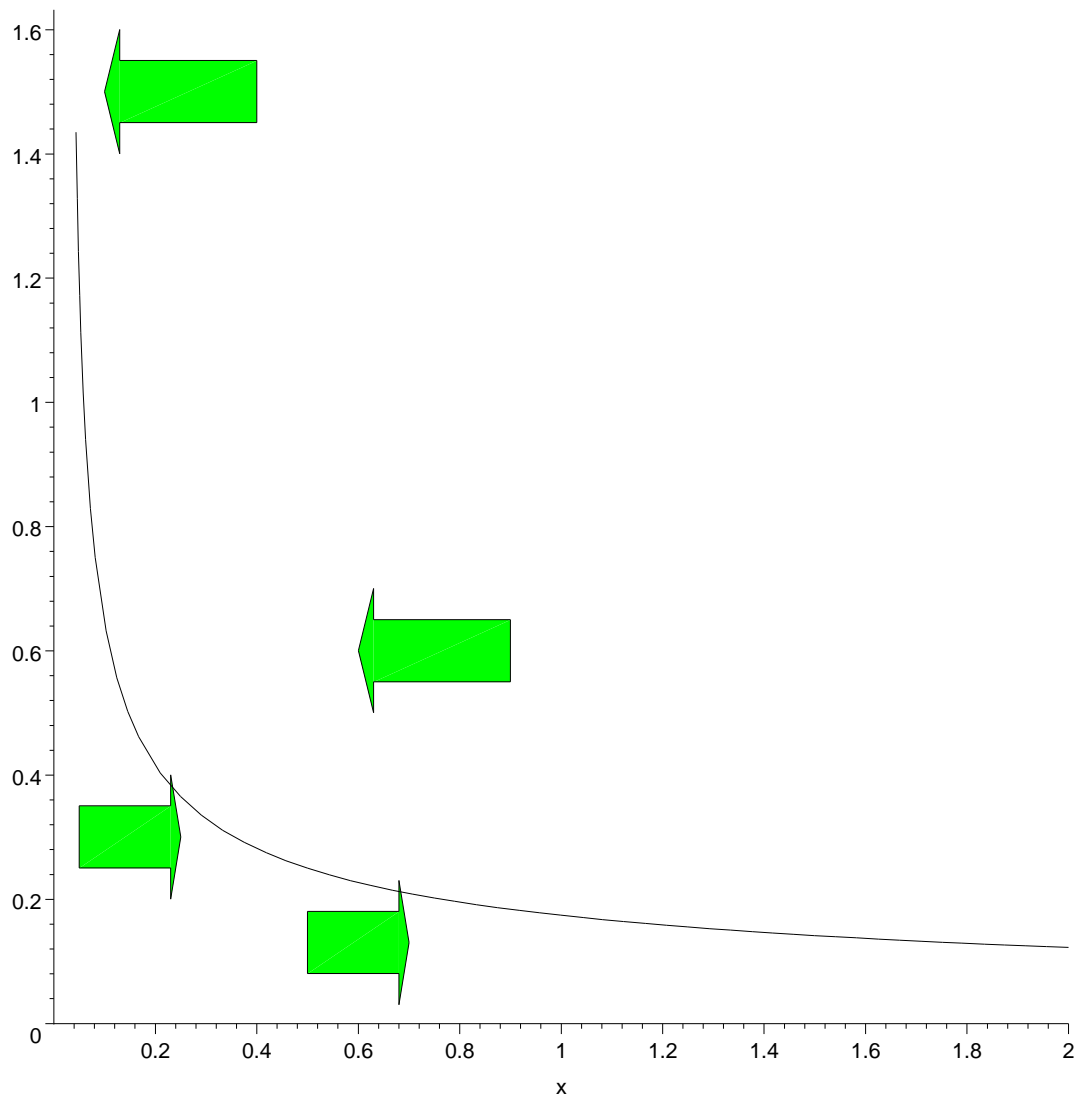
```
> arrow1 := arrow([0.9,0.6],[0.6,0.6], .1,.2,.1, color=green):
```

```
> arrow2 := arrow([0.5,0.13],[0.7,0.13], .1,.2,.1, color=green):
```

```
> arrow2b := arrow([0.05,0.3],[0.25,0.3], .1,.2,.1, color=green):
```

```
> arrow1b:= arrow([0.4,1.5],[0.1,1.5], .1,.2,.1, color=green):
```

```
> display(p1,arrow1,arrow2,arrow1b,arrow2b);
```



[> # when $x \sim 0$, we have that dy/dt is what sign?

[> eq2;

$$\frac{\alpha x y^g}{x y^g + y^g + 1} - \eta y$$

[> subs(x=0, eq2);

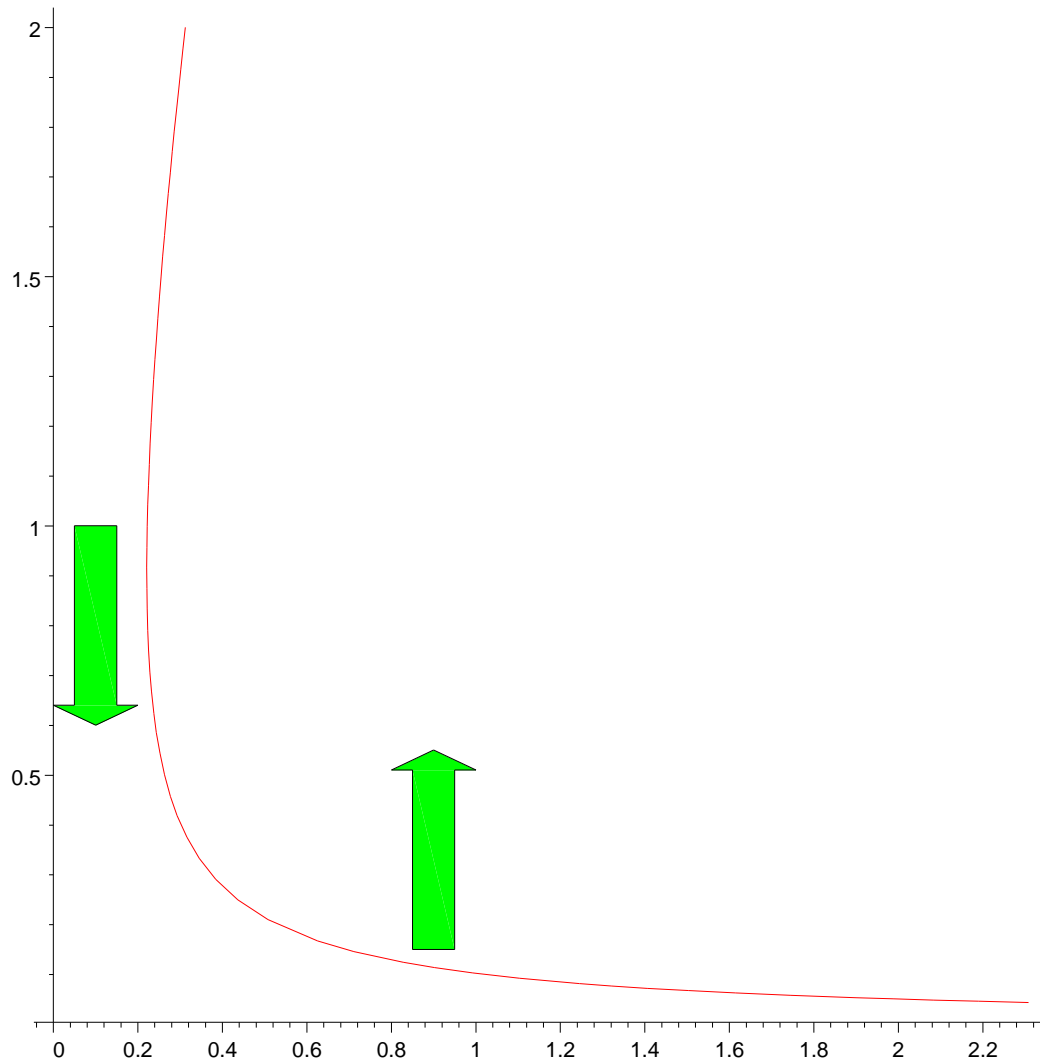
$$-\eta y$$

[> # so negative; while for $x \rightarrow \infty$: "a-by" which is positive for y small

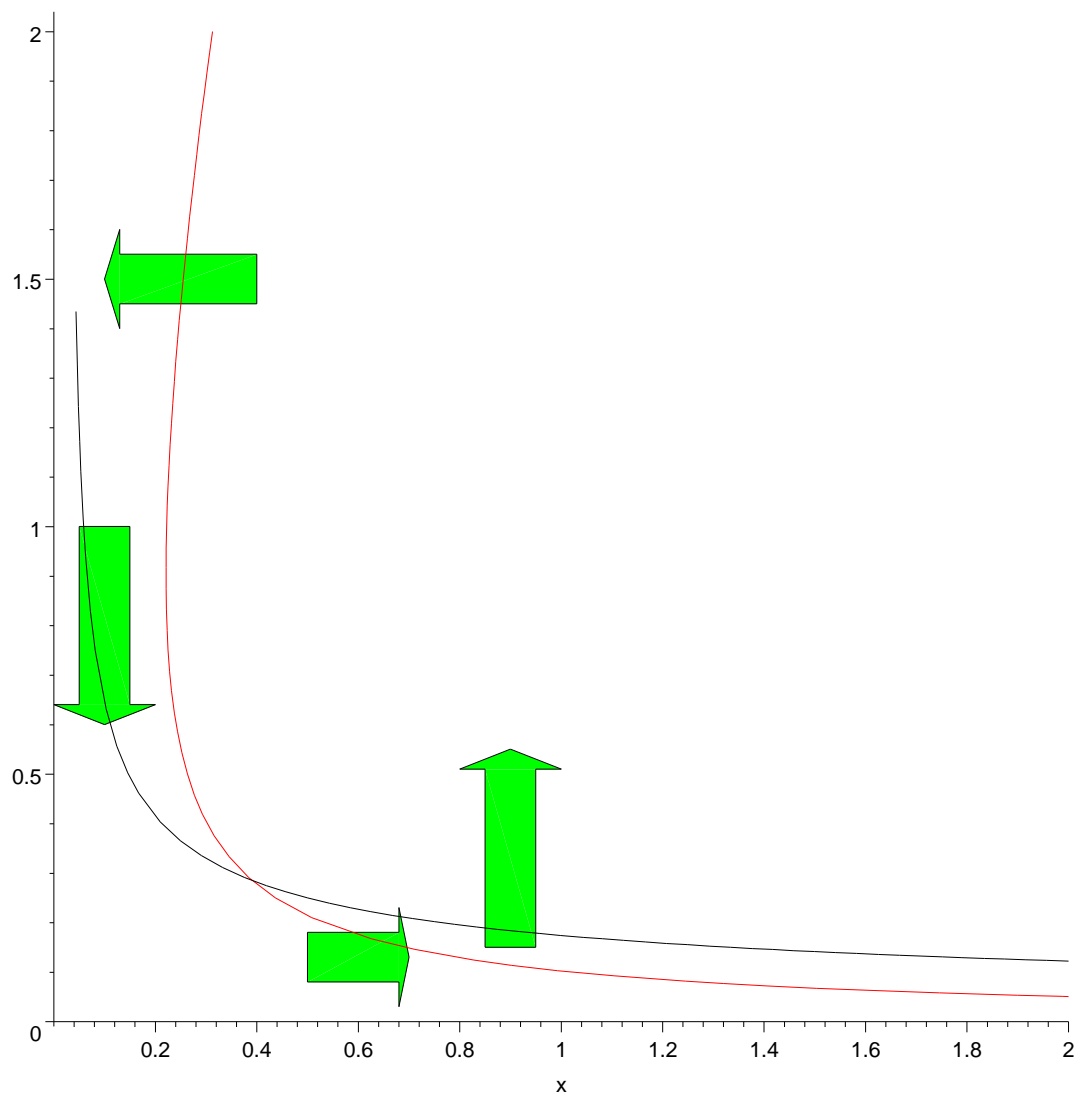
[> # and remember that direction can only change on the nullclines, by definition!

[

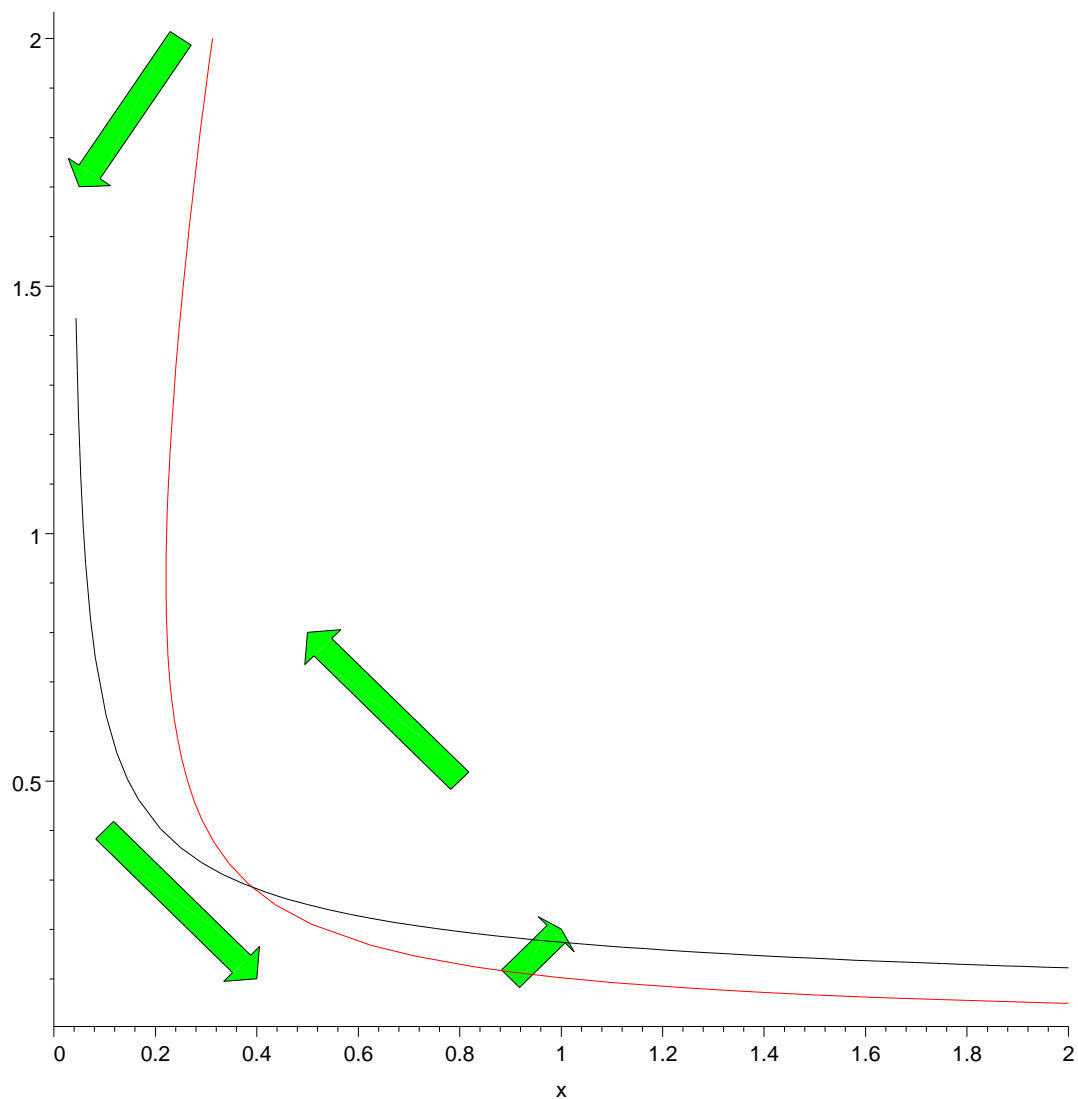
```
[ > arrow3 := arrow([0.1,1],[0.1,0.6], .1,.2,.1, color=green):  
[ > arrow4 := arrow([0.9,0.15],[0.9,0.55], .1,.2,.1, color=green):  
[ > display(p2,arrow3,arrow4);
```



```
[ > # so let's put everything together now:  
[ > display(p1,p2,arrow1b,arrow2,arrow3,arrow4);
```



```
[ > # so this gives the directions of motion in the 4 regions
[ > arrownw := arrow([0.8,0.5],[0.5,0.8], .05,.1,.1, color=green):
[ > arrowse := arrow([0.1,0.4],[0.4,0.1], .05,.1,.1, color=green):
[ > arrowsw := arrow([0.25,2],[0.05,1.7], .05,.1,.1, color=green):
[ > arrowne := arrow([0.9,0.1],[1,0.2], .05,.1,.1, color=green):
[ > display(p1,p2,arrowsw,arrowse,arrownw,arrowne);
```



```
[ > # looks like it could be a spiral or a periodic orbit
[ >
[ > # *** SEE SEPARATE FILE FOR TRAPPING REGION ARGUMENT !
[ >
[ > # so there is a trapping region - we expect Poincare-Bendixon
[   might help...
[ > # let's first sketch a phase plane and solution with Maple
[ > with(DEtools):
[ Warning, new definition for translate
[ > rhs1:=subs(consts,subs({x=x(t),y=y(t)},eq1));
```

$$rhs1 := .0285 - \frac{x(t) y(t)^2}{x(t) y(t)^2 + y(t)^2 + 1}$$

> rhs2:=subs(consts,subs({x=x(t),y=y(t)},eq2));

$$rhs2 := \frac{x(t) y(t)^2}{x(t) y(t)^2 + y(t)^2 + 1} - .1 y(t)$$

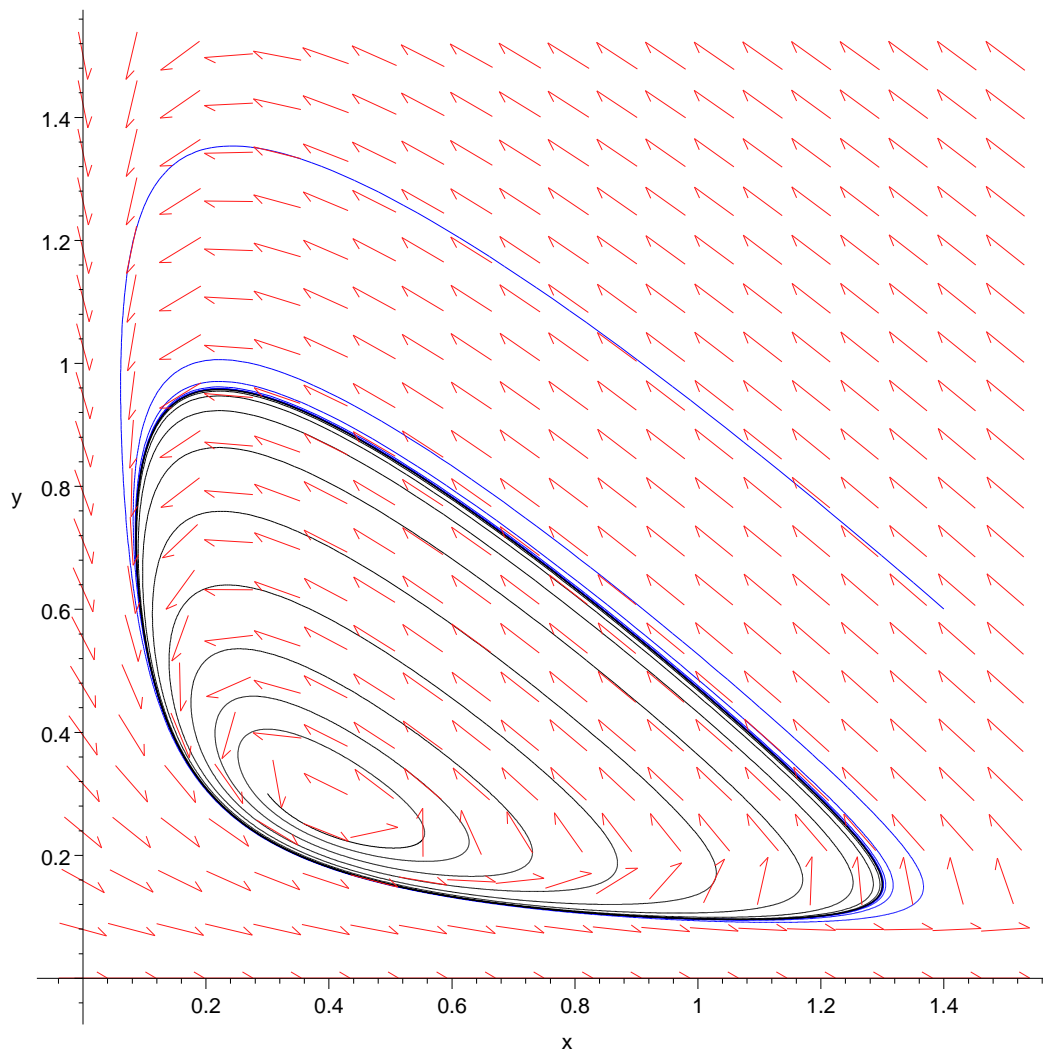
> eqn:=diff(x(t),t)=rhs1,diff(y(t),t)=rhs2;

$$eqn := \frac{\partial}{\partial t} x(t) = .0285 - \frac{x(t) y(t)^2}{x(t) y(t)^2 + y(t)^2 + 1}, \frac{\partial}{\partial t} y(t) = \frac{x(t) y(t)^2}{x(t) y(t)^2 + y(t)^2 + 1} - .1 y(t)$$

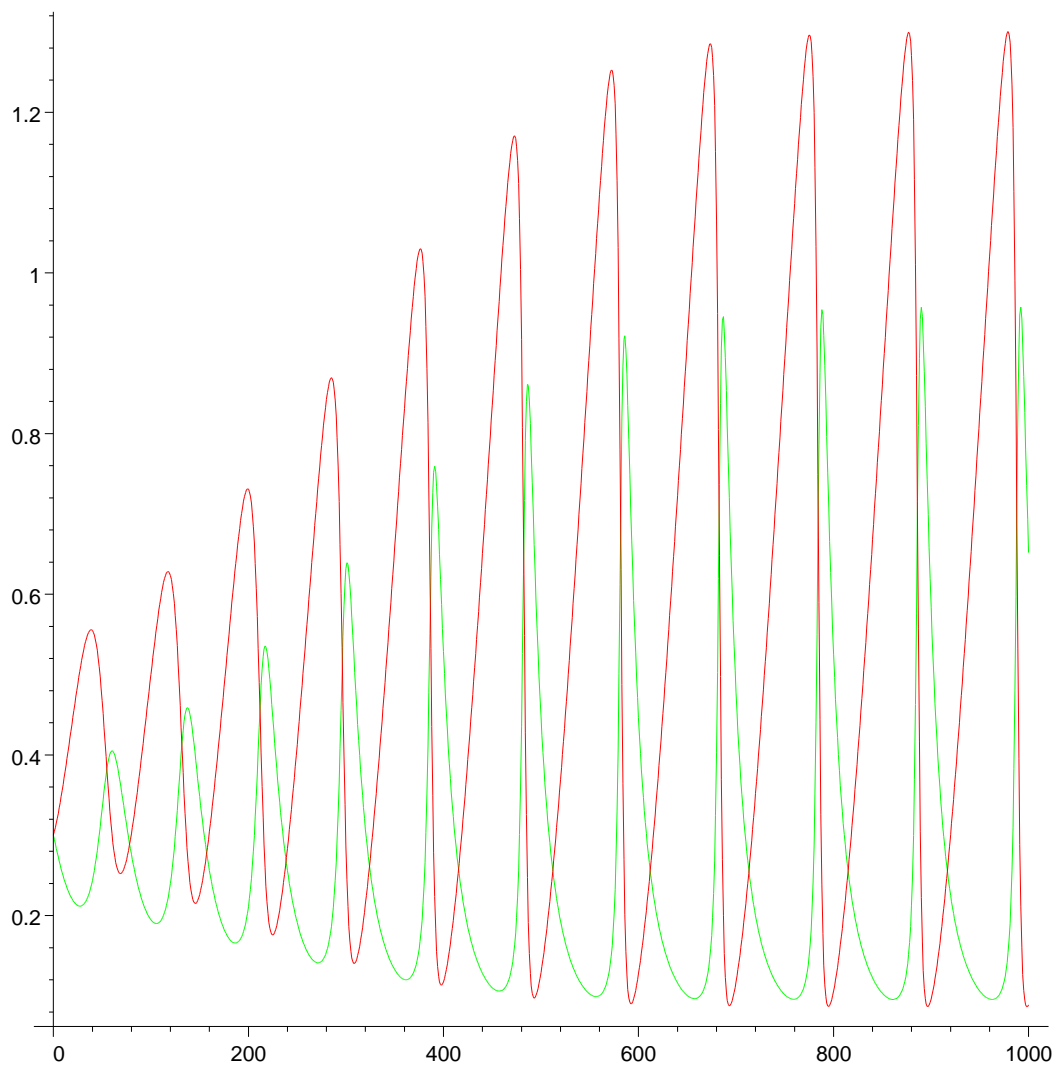
> init:=[[x(0)=0.3,y(0)=0.3],[x(0)=1.4,y(0)=0.6]];

$$init := [[x(0) = .3, y(0) = .3], [x(0) = 1.4, y(0) = .6]]$$

> DEplot([eqn],[x(t),y(t)],t=0..1000,init,x=0..1.5,y=0..1.5,linestyle=[black,blue],stepsize=0.1);



```
> # so we see a limit cycle, approached from inside (blue) and  
outside  
[ > # let's plot the blue trajectory as a function of t:  
[ > sol:=dsolve({eqn,x(0)=0.3,y(0)=0.3},{x(t),y(t)},type=numeric):  
[ > odeplot(sol,[[t,x(t)],[t,y(t)]],0..1000,numpoints=1000);
```



```
[ > # now let us study the problem more theoretically
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[ > with(linalg):
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```
Warning, new definition for adjoint
```

```
Warning, new definition for norm
```

```
[ Warning, new definition for trace
```

```
[ > F:=vector([eq1,eq2]);
```

$$F := \left[v - \frac{xy^g}{xy^g + y^g + 1}, \frac{\alpha xy^g}{xy^g + y^g + 1} - \eta y \right]$$

```
[ > Jac:=simplify(jacobian(F, [x,y]));
```

```
Jac :=
```

```

[

$$\begin{bmatrix} -\frac{y^{(2g)} + y^g}{(xy^g + y^g + 1)^2} & -\frac{xgy^{(g-1)}}{(xy^g + y^g + 1)^2} \\ \frac{\alpha(y^{(2g)} + y^g)}{(xy^g + y^g + 1)^2} & \frac{\alpha xy^{(g-1)}g - \eta x^2 y^{(2g)} - 2\eta xy^{(2g)} - 2\eta xy^g - \eta y^{(2g)} - 2\eta y^g - \eta}{(xy^g + y^g + 1)^2} \end{bmatrix}$$

> tr:=simplify(trace(Jac));

$$tr := \frac{-y^{(2g)} - y^g + \alpha xy^{(g-1)}g - \eta x^2 y^{(2g)} - 2\eta xy^{(2g)} - 2\eta xy^g - \eta y^{(2g)} - 2\eta y^g - \eta}{(xy^g + y^g + 1)^2}$$

> tr0:=simplify(subs(consts,subs({x=X,y=Y},tr)));
tr0 := .008801452057
> #so the trace is negative at the equilibrium, when using the above
params
> determ:=simplify(det(Jac));

$$determ := \frac{\eta(y^{(4g)}x^2 + 2y^{(4g)}x + 4y^{(3g)}x + y^{(4g)} + 3y^{(3g)} + 3y^{(2g)} + x^2y^{(3g)} + 2xy^{(2g)} + y^g)}{(xy^g + y^g + 1)^4}$$

> det0:=simplify(subs(consts,subs({x=X,y=Y},determ)));
det0 := .007090212492
> # and the det is positive - so we have an UNSTABLE equilibrium
> # the discriminant is:
> tr0^2-4*det0;
-.02828338441
> # negative, SO UNSTABLE SPIRAL
> # together with the "trapping region" argument, we know there's a
periodic orbit
> # which Maple already indicated too... it is really a limit cycle
> # how does this all depend on the actual parameters???
> # the DET is always > 0, as is clear from the formula above
(recall x, etc, all >0)
> # let's see what happens to the trace as we vary 'nu'
> # (non-dimensionalized rate of production of ATP, in 0..1 range):
> trac:=simplify(subs({x=X,y=Y},tr));

$$trac := -\left(\left(\frac{\alpha v}{\eta}\right)^{(2g)} + \left(\frac{\alpha v}{\eta}\right)^g - 2v\left(\frac{\alpha v}{\eta}\right)^g - g\eta + g\left(\frac{\alpha v}{\eta}\right)^g \eta v + g\eta v - g\left(\frac{\alpha v}{\eta}\right)^g \eta\right. \\ \left.+ \eta\left(\frac{\alpha v}{\eta}\right)^{(2g)} + 2\eta\left(\frac{\alpha v}{\eta}\right)^g + \left(\frac{\alpha v}{\eta}\right)^{(2g)}v^2 - 2\left(\frac{\alpha v}{\eta}\right)^{(2g)}v + \left(\frac{\alpha v}{\eta}\right)^g v^2 + \eta\right) / \\ \left(\left(\frac{\alpha v}{\eta}\right)^g + 1\right)^2$$

> factor(subs(nu=0,trac));

```

```

[
[ > factor(subs(nu=1, trac));
      
$$\eta(g-1) - \frac{\eta\left(\left(\frac{\alpha}{\eta}\right)^{2g} + 2\left(\frac{\alpha}{\eta}\right)^g + 1\right)}{\left(\left(\frac{\alpha}{\eta}\right)^g + 1\right)^2}$$

[ > simplify(%+eta);
      0
[ > # (sometimes Maple needs to be helped along :) so it equals -eta
[ > # so, assuming that g>1 (cooperativity), we see that the trace
[ > # (evaluated at the steady state, of course) is positive when nu=0
[ > # (instability),
[ > # and it is negative (stability) when the rate of production of
[ > # ATP is high
[ >

```